

## CH # 09 MACHINES

### MACHINES:

*"A machine is a device which converts a given form of energy into useful work in a convenient manner."*

### EFFORT:

*"Effort is the force directly applied on the machine for doing work."*

- It is represented by P.
- Unit of effort is Newton.

### LOAD:

*"It is the weight lifted or the resistance overcomes by machine."*

- It is represented by W.
- Unit of effort is Newton.

### MECHANICAL ADVANTAGE:

*"Mechanical advantage of the machine is the ratio of load and effort applied on it."*

$$\text{Mechanical advantage} = \frac{\text{Load}}{\text{Effort}}$$

$$\boxed{\text{M.A} = \frac{W}{P}}$$

- Mechanical advantage is the ratio of two similar quantities, therefore it has no unit.
- A machine who's M.A greater than "1" can lift heavier load by the application of smaller effort.

### INPUT:

*"Input is the work done "on" the machine by the effort."*

$$\text{Input} = \text{Effort} \times \text{Distance}$$

$$\text{Input} = P \times d$$

- Where "d" is the distance through which effort is applied.
- The unit of input is Joule.

### OUTPUT:

*"The useful work done "by" the machine is called output."*

$$\text{Output} = \text{Load} \times \text{Distance}$$

$$\text{Output} = W \times h$$

- Where "W" is the distance through which load moves.
- The unit of input is Joule.

### EFFICIENCY:

*"The ratio between the useful works done by the machine to the work done on the machine is called efficiency."*

$$\text{Efficiency} = \frac{\text{Output}}{\text{Input}} \times 100\%$$

$$\text{Efficiency} = \frac{W \times h}{P \times d} \times 100\%$$

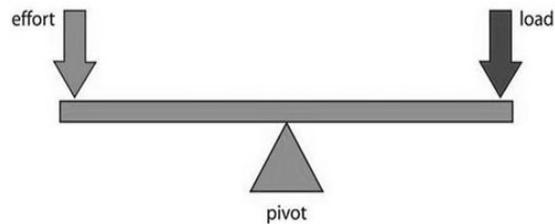
- Efficiency is the ratio of two similar quantities therefore it has no unit.
- It is expressed in percentage.

### TYPES OF SIMPLE MACHINE:

- i) Lever.
- ii) Wheel and axel.
- iii) Pulley.
- iv) Inclined plane.
- v) Wedge
- vi) Screw Jack.

#### i) LEVER:

*"It is simplest machine. It consists of rigid rod which can be rotated freely about a fixed point. Load can be lifted at one end of the lever by applying suitable effort at the end."*



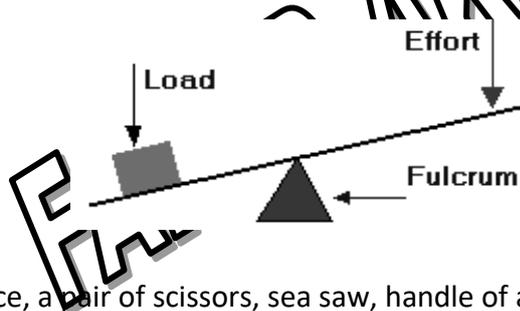
#### PARTS OF LEVER:

- **Fulcrum/pivot:**  
"It's a fixed point about which lever can be rotated."
- **Weight arm/effort:**  
"It is the perpendicular distance between the weight and the fulcrum."
- **Effort arm/load:**  
"It is the perpendicular distance between effort and fulcrum."

#### KINDS OF LEVER

##### Lever of first kind:

"In this kind of lever fulcrum is located between the effort and load."

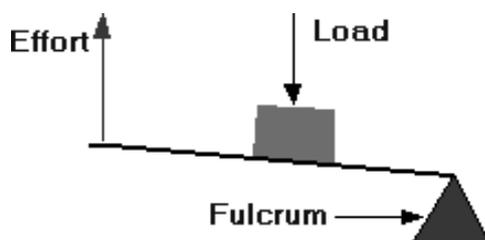


#### Example:

Common balance, a pair of scissors, sea saw, handle of a pump etc.

##### Lever of second kind:

"In this kind of lever weight is located between the fulcrum and effort."



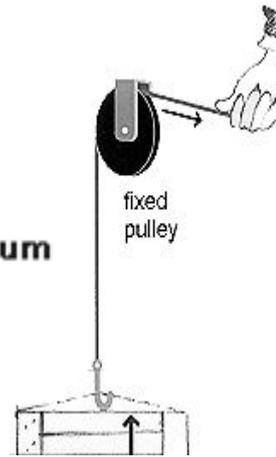
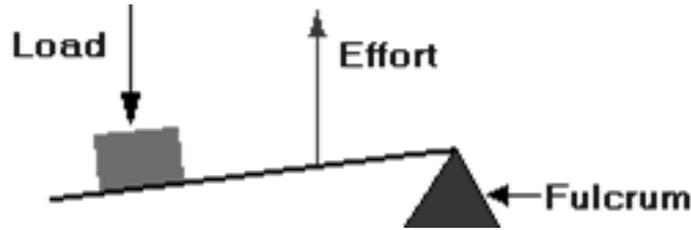
#### Examples:

Loader, Nut punching machine etc.

cracker, the door, bottle opener,

##### Lever of third kind:

"In this kind of lever the effort is between fulcrum and weight."



**Example:**

Fire tong, human force arm, upper and lower jaws in the mouth.

**PRINCIPLE OF LEVER:**

"Torque of the effort is equal to the torque of the weight."

Torque of effort = torque of weight

But,

Torque of effort = Effort x effort arm

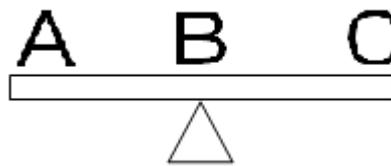
Torque of weight = Weight x weight arm

Hence,

$\text{Effort} \times \text{effort arm} = \text{weight} \times \text{weight arm}$
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**MECHANICAL ADVANTAGE OF LEVER (M.A):**

Let "AB" be the effort arm and "BC" be the weight arm of a lever then according to the principle of lever.



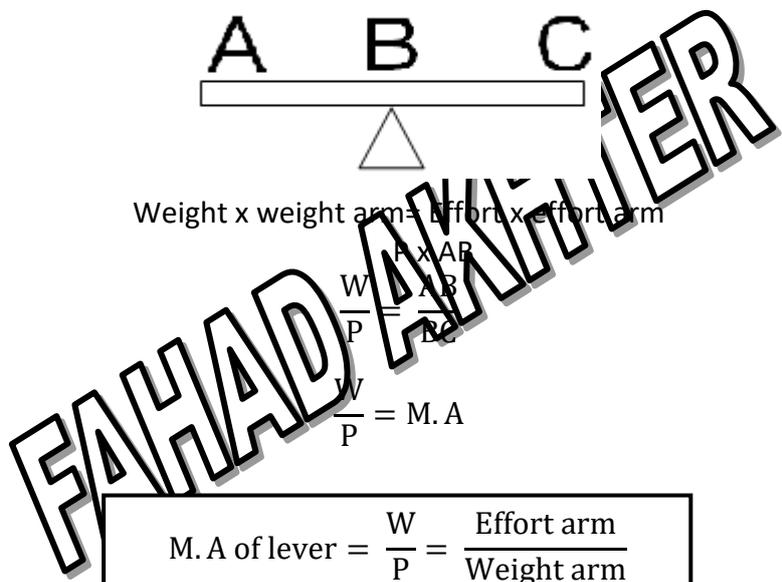
Weight x weight arm = Effort x effort arm

$W \times BC =$

$$P \times AB$$

$$\frac{W}{P} = \frac{AB}{BC}$$

$$\frac{W}{P} = M.A$$



$M.A \text{ of lever} = \frac{W}{P} = \frac{\text{Effort arm}}{\text{Weight arm}}$
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M.A of lever can be increased by increasing the effort arm as compared to weight arm.

**ii) PULLEY:**

"A grooved wheel mounted on an axle is called pulley"

The axle is fixed to the frame which is known as Block A rope is passing through the groove round the pulley is used to rotate pulley in a block about axle It help us to change the direction of the applied force.

**TYPES OF PULLEY**

Basically pulleys are of two types:

1. Fixed pulley.
2. Movable Pulley.

### 1. FIXED PULLEY:

*“Fixed pulley is that whose block is fixed to a strong beam or ceiling the pulley does not move is called fixed pulley”*

#### MECHANICAL ADVANTAGE OF FIXED PULLEY:

Assuming that the pulley to be frictionless and neglecting the weight of the rope we can write:

Weight x distance through which weight is lifted = Effort x distance through which effort is acts

$$\frac{W}{P} = \frac{\text{Effort x distance through which effort is acts}}{\text{distance through which weight is lifted}}$$

In a fixed pulley the distance through which weight is lifted is equal to the distance through which effort is applied, hence:

$$\frac{W}{P} = 1$$

### 2. MOVEABLE PULLEY:

*“In this pulley, one end of the rope which is passing around the pulley is tied to a firm support and effort “P” is applied at its other end the load or weight “W” to be lifted, the hung from the hook of the block”*

#### MECHANICAL ADVANTAGE OF MOVEABLE PULLEY:

The moveable pulley move upward from the two sides therefore

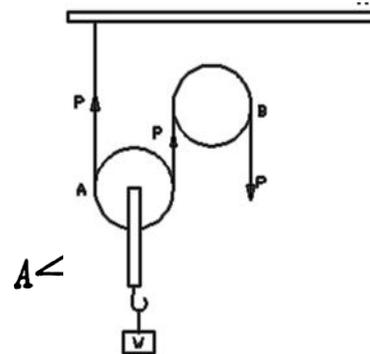
$$2P = W$$

$$\text{M. A of fixed pulley} = \frac{W}{P}$$

### iii) INCLINED PLANE:

*“Inclined plane is a plane surface which makes a certain angel “θ” with the horizontal.”*

- Inclined plane is a simple machine it help us to raises heavy load by applying a relatively much smaller force.



#### MECHANICAL ADVANTAGE OF INCLINED PLANE:

In order to raise load “W” the effort “P” must be applied parallel to the plane if effort is applied through a distance “l” due to which load is lifted through height “h” then for a frictionless inclined plane:

$$\text{Output} = \text{Input}$$

$$W \times h = P \times l$$

$$\frac{W}{P} = \frac{l}{h}$$

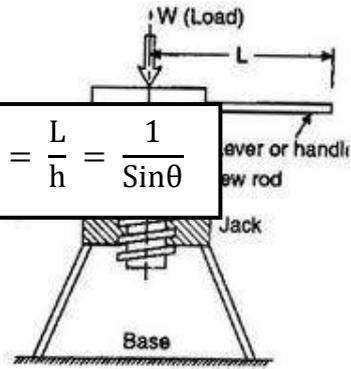
$$\text{M. A of inclined plane} = \frac{W}{P} = \frac{l}{h}$$

If the inclined plane makes a certain angle “θ” with the horizontal then:

$$\sin \theta = \frac{h}{L}$$

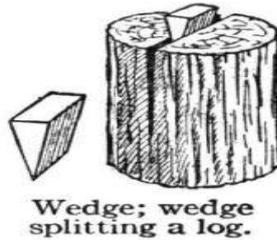
$$\frac{L}{h} = \frac{1}{\sin \theta}$$

$$\text{M. A of inclined plane} = \frac{W}{P} = \frac{L}{h} = \frac{1}{\sin \theta}$$



**iv) WEDGE:**

“Wedge is simple machine it is made up two inclined planes together. It is used to cut wood or use as a fulcrum in lever”



**MECHANICAL ADVANTAGE OF WEDGE:**

$$\text{M. A of wedge} = \frac{\text{Length of the incline surface of a wedge}}{\text{Thickness of the wedge}}$$

\*M.A of sharp wedge is high.

**v) SCREW:**

“Screw is a simple machine. It consist of a threaded rod with a head called screw head.”

**MECHANICAL ADVANTAGE OF SCREW:**

To turn the screw effort “P” is applied at the screw head. Let “d” be the radius and effort acts along a distance of  $2\pi d$ . As a result screw covered distance “h”. The screw overcomes an opposition “W” then:

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$$\text{Output} = \text{input}$$

$$W \times h = P \times 2\pi d$$

$$\frac{W}{P} = \frac{2\pi d}{h}$$

**vi) SCREW JACK** Mechanical advantage of screw =  $\frac{W}{P} = \frac{2\pi d}{h}$

“Screw jack is a simple machine used to raise the automobile. It consists of a long threaded rod passing through a threaded block. A handle is also provided to turn the thread block.”

**Mechanical advantage of screw jack:**

If the length of the handle is “d”, the effort “P” applied at the end of the handle acts along a circle of radius “d” and covers a distance of  $2\pi d$  where as for each revolution the block lifts the load through a distance “h” then:

$$\text{Output} = \text{Input}$$

$$W \times h = P \times 2\pi d$$



$$\frac{W}{P} = \frac{2\pi d}{h}$$

$$\text{Mechanical advantage of screw jack} = \frac{W}{P} = \frac{2\pi d}{h}$$

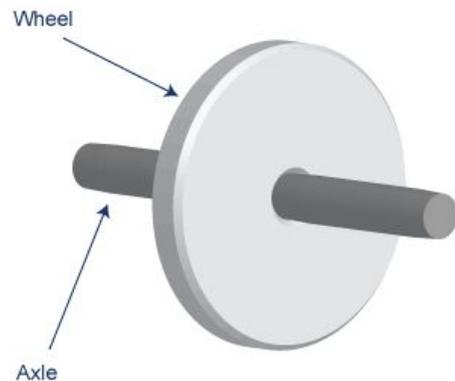
**vii) WHEEL AND AXLE:**

*“Wheel and axle is a simple machine. It consists of wheel of large radius “R” and the cylinder of smaller radius “r”, the cylinder is called wheel and axel.”*

**MECHANICAL ADVANTAGE OF WHEEL AND AXLE:**

Effort “P” is applied on the rim of the wheel and load is lifted by a string wound round the axle. Hence for one rotation effort “P” acts along a distance  $2\pi R$  and the load “W” raises through a distance  $2\pi r$  then:

$$\begin{aligned} \text{Output} &= \text{Input} \\ W \times 2\pi r &= P \times 2\pi R \\ \frac{W}{P} &= \frac{2\pi R}{2\pi r} \end{aligned}$$



$$\text{Mechanical advantage of wheel and axle} = \frac{W}{P} = \frac{R}{r}$$

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